

EFFICIENT COSMOLOGICAL MODEL SELECTION USING BAYESIAN OPTIMISATION

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Bayesian model comparison

Model M_0 vs M_1 given data D , the Bayesian way:

$$\frac{P(M_0|D)}{P(M_1|D)} = B_{01} \frac{P(M_0)}{P(M_1)}, \quad B_{01} = \frac{P(D|M_0)}{P(D|M_1)}$$

$$\underbrace{\mathcal{Z} = P(D|M)}_{\text{Bayesian evidence}} = \int \underbrace{P(D|M, \theta)P(\theta|M)}_{\text{Posterior} = \text{Likelihood} \times \text{Prior}} d\theta$$

$\mathcal{Z}$ can be computed from MCMC chains (Savage–Dickey density ratio) or using nested sampling.

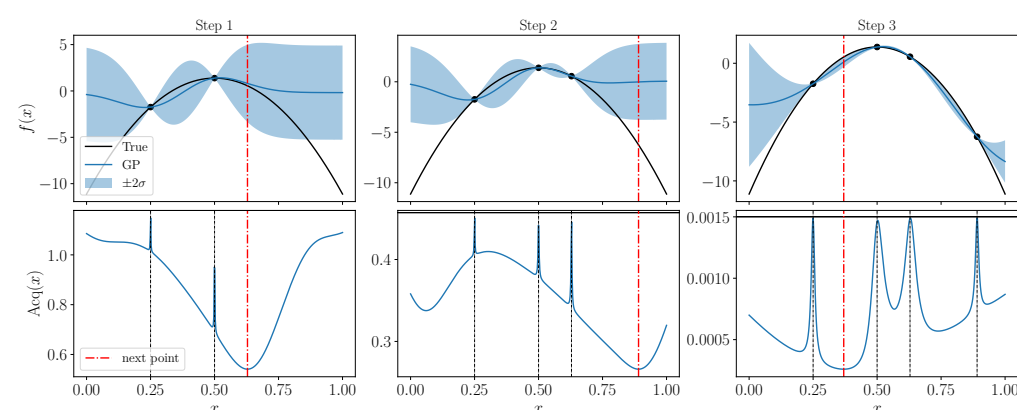
Bayesian Optimisation (BO)

When to use it?

MCMC/nested sampling not feasible for *slow to evaluate* likelihoods – instead *train a fast surrogate of the likelihood using BO*, then run MCMC/nested sampling on surrogate.

How does it work?

Uses *mean of Gaussian process* (GP) [1] as surrogate for the (log)-likelihood + *active acquisition strategy* to train the GP. Uncertainty of GP $\rightarrow \Delta \log \mathcal{Z}$ for *convergence control*.



Bayesian Optimisation in action.

Algorithm

- Input:** GP μ , acquisition α , $\Delta \log \mathcal{Z}$ threshold ϵ , max steps N
- 1: Initialise training set $\mathcal{D}$ with random Sobol points
 - 2: **while** $i < N$ and $\neg$ converged **do**
 - 3: $x_i \leftarrow \arg \min_x \alpha(x | \mu, \mathcal{D})$, $y_i \leftarrow f(x_i)$
 - 4: $\mathcal{D} \leftarrow \mathcal{D} \cup \{(x_i, y_i)\}$
 - 5: Update μ with $\mathcal{D}$
 - 6: converged=True if $\Delta \log \mathcal{Z} \leq \epsilon$ else False
 - 7: $i \leftarrow i + 1$
 - 8: **end while**
 - 9: **return** samples from *surrogate* posterior μ , final $\log \mathcal{Z}$, $\Delta \log \mathcal{Z}$

Pros

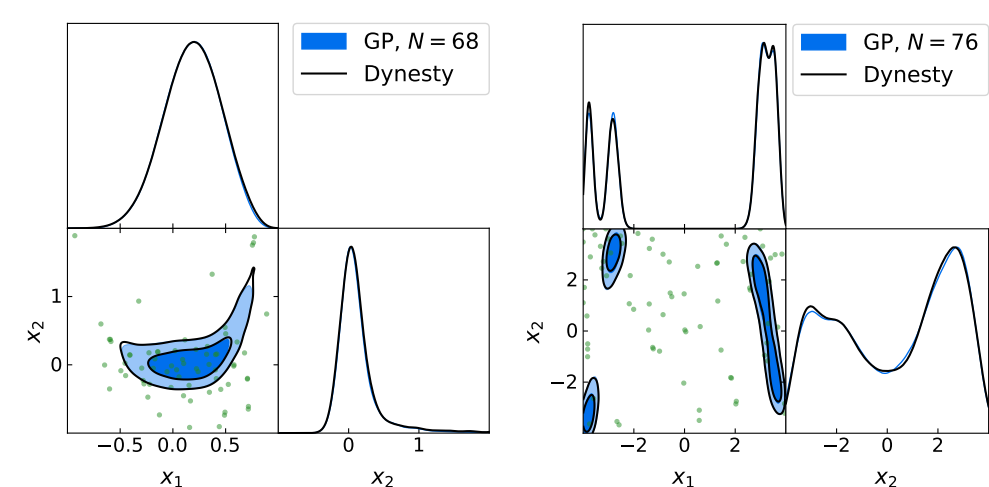
Fast GP surrogate ($\gtrsim 1000$ eval/sec). 10–100 times *fewer likelihood evals* required compared to traditional methods, *overall faster for slow likelihoods* ($t \gtrsim 1$ s).

Cons

Greater computational overhead of intermediate steps.
Limited to $N_{\text{dim}} \lesssim 20$.

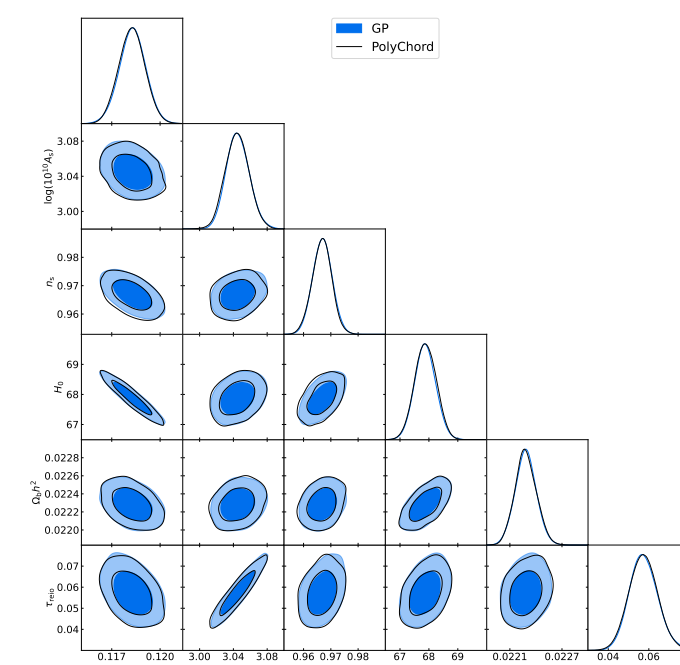
Results

Test functions



BO vs nested sampler dynesty [2]. Green dots = GP training points (N) from BO.

Cosmology



Λ CDM from DESI+Planck CamSpec (9 nuisance params). BO with $N \sim 900$ likelihood evals and runtime ~ 10 hours, $\log \mathcal{Z} = -5529.48^{+2.5}_{-0.6}$, excellent agreement with PolyChord [3].

Prev. applications in cosmology – for global optimisation [4], and parameter posteriors [5]. *We build on these but differ in GP, acquisition and convergence choices.*

Paper (more examples) + code (JAX based) out soon.
If interested in applications, please get in touch!

References

- [1] C. K. Williams and C. E. Rasmussen, *Gaussian Processes for Machine Learning*. MIT Press Cambridge, MA, 2006.
- [2] J. S. Speagle, *dynesty: a dynamic nested sampling package for estimating bayesian posteriors and evidences*, *Monthly Notices of the Royal Astronomical Society* **493** (Feb., 2020) 3132–3158.
- [3] W. J. Handley, M. P. Hobson and A. N. Lasenby, *PolyChord: nested sampling for cosmology*, *Mon. Not. Roy. Astron. Soc.* **450** (2015) L61–L65, [1502.01856].
- [4] J. Hamann and J. Wons, *Optimising inflationary features the Bayesian way*, *JCAP* **03** (2022) 036, [2112.08571].
- [5] J. E. Gammal, N. Schöneberg, J. Torrado and C. Fidler, *Fast and robust Bayesian inference using Gaussian processes with GPry*, *JCAP* **10** (2023) 021, [2211.02045].